

# Ill-Posed Operator Equations and an Inverse Problem in PDE

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# Ill-Posed Operator Equations

Let  $T : X \rightarrow Y$  be a linear operator between normed linear spaces.

The problem of solving the operator equation

$$Tx = y \quad (*)$$

for  $y \in Y$  is said to be **ill-posed** if it does not have a unique solution which depends continuously on the data  $y$ .

## Theorem

If  $T$  is not bounded below, then  $(*)$  is ill-posed.

In fact, if  $y \in R(T)$  and  $Tx = y$ , then for every  $\varepsilon > 0$ , there exists  $y_\varepsilon \in Y$  and  $x_\varepsilon \in X$  such that  $Tx_\varepsilon = y_\varepsilon$  and

$$\|y - y_\varepsilon\| \leq \varepsilon$$

but

$$\|x - x_\varepsilon\| \geq \frac{1}{\varepsilon}.$$

- Given any sequence  $(\alpha_n)$  of positive real numbers such that  $\alpha_n \rightarrow 0$  and  $n \rightarrow \infty$ , there there exists  $y_n \in Y$  and  $x_n \in X$  such that  $Tx_n = y_n$  and

$$\|y - y_n\| \leq \alpha_n \quad \text{but} \quad \|x - x_n\| \geq \frac{1}{\alpha_n}$$

for all  $n \in \mathbb{N}$ .

## Proof of the theorem.

Since  $T$  is not bounded below, for every  $\varepsilon > 0$ , there exists  $u_\varepsilon \in X$  with  $\|u_\varepsilon\| = 1$  such that

$$\|Tu_\varepsilon\| < \varepsilon^2 \|u_\varepsilon\| = \varepsilon.$$

Let

$$x_\varepsilon = x + \frac{1}{\varepsilon} u_\varepsilon, \quad y_\varepsilon = Tx_\varepsilon.$$

Then  $Tx_\varepsilon = Tx + \frac{1}{\varepsilon} Tu_\varepsilon$  so that

$$\|Tx_\varepsilon - Tx\| = \frac{1}{\varepsilon} \|Tu_\varepsilon\| < \varepsilon.$$

Note that

$$\|x_\varepsilon - x\| = \frac{1}{\varepsilon} \|u_\varepsilon\| = \frac{1}{\varepsilon}.$$



## Corollary

If  $X$  is infinite dimensional and  $T$  is a compact operator, then  $(*)$  is ill-posed.

## Proof.

A compact operator on an infinite dimensional normed linear space is not bounded below. □

- Recall that if  $k(\cdot, \cdot) \in L^2(\Omega \times \Omega)$ , where  $\Omega$  is a bounded open set in  $\mathbb{R}^k$ , the operator  $T$  defined by

$$(Tx)(s) := \int_{\Omega} k(s, \zeta)x(\zeta)d\zeta, \quad x \in L^2(\Omega),$$

is a compact operator from the infinite dimensional space  $L^2(\Omega)$  into itself.

# An illustration

Let  $X$  and  $Y$  be Hilbert spaces and  $T : X \rightarrow Y$  be a compact operator of infinite rank. Let

$$Tx := \sum_{n=1}^{\infty} \sigma_n \langle x, u_n \rangle v_n, \quad x \in X,$$

be a **singular value decomposition**<sup>1</sup> of  $T$ .

Let  $y \in Y$ .

- For  $y$  to be in  $R(T)$ , it is necessary that

$$\sum_{n=1}^{\infty} \frac{|\langle y, v_n \rangle|^2}{\sigma_n^2} < \infty$$

and in that case,  $Tx = y$ , where

$$x = \sum_{n=1}^{\infty} \frac{\langle y, v_n \rangle}{\sigma_n} u_n \in N(T)^\perp.$$

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<sup>1</sup>See M.T. Nair, *Functional Analysis: A First Course*, PHI Learning.

For  $k \in \mathbb{N}$ , let  $x_k = x + \frac{1}{\sqrt{\sigma_k}} u_k$ . Then

$$\|Tx - Tx_k\| = \frac{1}{\sqrt{\sigma_k}} \|Tu_k\| = \sqrt{\sigma_k},$$

but

$$\|x - x_k\| = \frac{1}{\sqrt{\sigma_k}}.$$

- As  $k \rightarrow \infty$ ,

$$\|Tx - Tx_k\| \rightarrow 0 \quad \text{but} \quad \|x - x_k\| \rightarrow \infty.$$

# Backward heat conduction problem

- Find  $u(\cdot, t) \in L^2[0, \ell]$  such that

$$\frac{\partial u}{\partial t} = c^2 \frac{\partial^2 u}{\partial x^2}, \quad 0 < x < \ell, \quad 0 < t < \tau, \quad (1)$$

$$u(0, t) = 0 = u(\ell, t), \quad (2)$$

from the knowledge of the final value

$$u(\cdot, \tau) := g.$$



# Recall:

For  $f \in L^2[0, \ell]$ ,

$$u(x, t) = \sum_{n=1}^{\infty} e^{-\lambda_n^2 t} \langle f, \varphi_n \rangle \varphi_n(x), \quad (*)$$

with

$$\lambda_n := \frac{n\pi c}{\ell}, \quad \varphi_n(x) := \sqrt{\frac{2}{\ell}} \sin\left(\frac{n\pi}{\ell} x\right)$$

satisfies the equations (1) and (2) and the initial condition

$$u(\cdot, 0) = f.$$

- Knowing  $f := u(\cdot, 0)$ , we obtain  $u(\cdot, t)$  in a stable manner.

# Inverse problem

- From the knowledge of  $g := u(\cdot, \tau)$ , find  $f := u(\cdot, t)$  for  $0 \leq t < \tau$ .

From (\*),

$$u(x, \tau) = \sum_{n=1}^{\infty} e^{-\lambda_n^2 \tau} \langle f, \varphi_n \rangle \varphi_n(x). \quad (**)$$

and

$$\langle f, \varphi_n \rangle = e^{\lambda_n^2 t} \langle u(\cdot, t), \varphi_n \rangle.$$

Hence, from (\*\*),

$$u(x, \tau) = \sum_{n=1}^{\infty} e^{-\lambda_n^2 (\tau - t)} \langle u(\cdot, t), \varphi_n \rangle \varphi_n(x).$$

This is same as solving the operator equation:

$$Af = g,$$

where

$$A\varphi := \sum_{n=1}^{\infty} e^{-\lambda_n^2(\tau-t)} \langle \varphi, \varphi_n \rangle \varphi_n.$$

Note that  $A$  is a **compact, positive, self adjoint operator** on  $L^2[0, \ell]$  with eigenvalues

$$\mu_n := e^{-\lambda_n^2(\tau-t)}.$$

- $\mu_n \rightarrow 0$  exponentially!
- The inverse problem is **severly ill-posed!**

$\Omega$ : bounded domain in  $\mathbb{R}^k$ ;

$$\frac{\partial u}{\partial t} = c^2 \Delta u, \quad (x, t) \in \Omega \times [0, \tau],$$

$$u(x, t) = 0, \quad x \in \partial\Omega, t \in [0, \tau).$$

In this case,  $u(\cdot, 0) = f$  implies

$$u(x, t) = \sum_{n=1}^{\infty} e^{-\lambda_n^2 t} \langle f, \varphi_n \rangle \varphi_n(x), \quad (*)$$

with

$$-\Delta \varphi_n = \lambda_n \varphi_n, \quad n \in \mathbb{N};$$

and  $\{\varphi_n : n \in \mathbb{N}\}$  is an orthonormal basis of  $L^2(\Omega)$ .

- **BHCP:** From the knowledge of  $g := u(\cdot, \tau)$  determine  $f := u(\cdot, t)$ .

# Regularization - Stable approximation method

Since a compact operator equation is ill-posed,

*Small error in the data can cause large deviation in the solution.*

- One has to use some regularization method for obtaining stable approximation methods.

We shall consider one such method, the so called, *spectral cut-off method*.

# Spectral cut-off method:

Recall: If  $T : X \rightarrow Y$  is a compact operator of infinite rank, and if

$$T = \sum_{n=1}^{\infty} \sigma_n \langle \cdot, u_n \rangle v_n$$

is an SVD of  $V$ , and if  $y \in R(T)$ , then

$$x := \sum_{n=1}^{\infty} \frac{\langle y, v_n \rangle}{\sigma_n} u_n$$

belongs to  $N(T)^\perp$  and  $Tx = y$ .

A natural way of approximating  $x$  would be to take a  $k$ -th cut-off of  $x$ :

$$x_k := \sum_{n=1}^k \frac{\langle y, v_n \rangle}{\sigma_n} u_n.$$

Clearly,

$$\|x - x_k\|^2 = \sum_{n=k+1}^{\infty} \frac{|\langle y, v_n \rangle|^2}{\sigma_n^2} \rightarrow 0$$

as  $k \rightarrow \infty$ .

Suppose the data  $y$  is noisy, i.e., we have  $\tilde{y}$  in place of  $y$ . Then one may take the approximation as

$$\tilde{x}_k := \sum_{n=1}^k \frac{\langle \tilde{y}, v_n \rangle}{\sigma_n} u_n.$$

Then

$$x_k - \tilde{x}_k = \sum_{n=1}^k \frac{\langle y - \tilde{y}, v_n \rangle}{\sigma_n} u_n.$$

$$\begin{aligned}
\|x - \tilde{x}_k\|^2 &= \|x - x_k\|^2 + \|x_k - \tilde{x}_k\|^2 \\
&= \|x - x_k\|^2 + \sum_{n=1}^k \frac{|\langle y - \tilde{y}, v_n \rangle|^2}{\sigma_n^2} \\
&\geq \|x - x_k\|^2 + \frac{|\langle y - \tilde{y}, v_k \rangle|^2}{\sigma_k^2}.
\end{aligned}$$

Thus,

$$\|x - \tilde{x}_k\|^2 \geq \|x - x_k\|^2 + \frac{|\langle y - \tilde{y}, v_k \rangle|^2}{\sigma_k^2}$$

and

$$\|x - \tilde{x}_k\|^2 \leq \|x - x_k\|^2 + \frac{\delta^2}{\sigma_k^2}.$$



In particular, if  $\tilde{y} := y + \delta v_k$ , then  $\|y - \tilde{y}\| = \delta$  and

$$\|x - \tilde{x}_k\|^2 = \|x - x_k\|^2 + \frac{\delta^2}{\sigma_k^2}. \quad (*)$$

- For fixed  $\delta$ ,  $\|x - \tilde{x}_k\|$  can be large (for large  $k$ ).
- Rate of convergence cannot be ascertained without having *source conditions* on  $x$ :

# Estimate under source condition(s)

Recall

$$\|x - x_k\|^2 = \sum_{n=k+1}^{\infty} |\langle x, u_n \rangle|^2.$$

Suppose:

$$x \in R(T^*) \quad \text{so that} \quad x = T^*u. \quad (**)$$

Then,

$$\begin{aligned} \|x - x_k\|^2 &= \sum_{n=k+1}^{\infty} |\langle T^*u, u_n \rangle|^2 = \sum_{n=k+1}^{\infty} |\langle u, Tu_n \rangle|^2 \\ &= \sum_{n=k+1}^{\infty} \sigma_n^2 |\langle u, v_n \rangle|^2 \leq \|u\|^2 \sigma_{k+1}^2. \end{aligned}$$

(\*) and (\*\*) imply:

$$\|x - \tilde{x}_k\|^2 \leq \|u\|^2 \sigma_{k+1}^2 + \frac{\delta^2}{\sigma_{k+1}^2}$$

- Note that

$$x \in R(T^*) \iff \sum_{n=1}^{\infty} \frac{|\langle x, u_n \rangle|^2}{\sigma_n^2} < \infty.$$

### Theorem

Suppose  $x \in R(T^*)$  with  $x = T^*u$  and  $k$  is such that  $\delta \leq \sigma_{k+1}^2$ , then

$$\|x - \tilde{x}_k\|^2 \leq (1 + \|u\|^2) \sigma_{k+1}^2.$$

More generally:

### Theorem

If  $x \in R((T^*T)^\nu)$  and  $k$  is such that  $\delta \leq \sigma_{k+1}^{2\nu+1}$ , then

$$\|x - \tilde{x}_k\|^2 = O(\sigma_{k+1}^{2\nu+1}).$$

# IVP for a Parabolic Problem

- $H$ : a Hilbert space;
- $A : D(A) \subseteq H$ : a densely defined positive self adjoint unbounded operator.

Given  $\varphi_0 \in H$  and  $f \in L^1([0, \infty), H)$ , consider the initial value problem (IVP):

$$\frac{d}{dt}u(t) + Au(t) = f(t), \quad u(0) = \varphi_0. \quad (1)$$

Known<sup>2</sup>:

$$u(t) = e^{-tA}\varphi_0 + \int_0^t e^{-(t-s)A}f(s)ds.$$

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<sup>2</sup>See: A. Pazy, *Semigroups of Linear Operators and Applications to PDE*, Springer-Verlag, 1983

Here, the operator  $e^{-tA}$  is defined by

$$e^{-tA}\varphi := \int_0^\infty e^{-t\lambda} dE_\lambda \varphi.$$

where  $\{E_\lambda : \lambda \geq 0\}$  is the resolution of identity of  $A$ .

- $\|e^{-tA}\varphi\|^2 := \int_0^\infty e^{-2t\lambda} d\|E_\lambda \varphi\|^2 \leq \int_0^\infty d\|E_\lambda \varphi\|^2 = \|\varphi\|^2.$

Recall spectral theorem:

*There exists a resolution of identity  $\{E_\lambda : \lambda \geq 0\}$  such that*

$$A\varphi = \int_0^\infty \lambda dE_\lambda \varphi, \quad \varphi \in D(A),$$

*and in that case  $D(A) := \{\varphi \in H : \int_0^\infty \lambda^2 d\|E_\lambda \varphi\|^2\}$ .*

- For any continuous function  $g : [0, \infty) \rightarrow \mathbb{R}$ ,

$$g(A)\varphi := \int_0^\infty g(\lambda) dE_\lambda \varphi, \quad \varphi \in D(g(A))$$

is a self adjoint operator with

$$D(g(A)) := \{\varphi \in H : \int_0^\infty |g(\lambda)|^2 d\|E_\lambda \varphi\|^2\}.$$

- For  $\varphi \in D(g(A))$ ,

$$\|g(A)\varphi\|^2 := \int_0^\infty |g(\lambda)|^2 d\|E_\lambda \varphi\|^2.$$

In particular, we have the following:

- For  $t \geq 0$

$$e^{tA}\varphi := \int_0^\infty e^{t\lambda} dE_\lambda \varphi, \quad \varphi \in D(e^{tA}),$$

where

$$D(e^{tA}) := \left\{ \varphi \in H : \int_0^\infty e^{2t\lambda} d\|E_\lambda \varphi\|^2 \right\}$$

and

$$\|e^{tA}\varphi\|^2 = \int_0^\infty e^{2t\lambda} d\|E_\lambda \varphi\|^2 \geq \|\varphi\|^2.$$

- $e^{tA}$  is one-one, onto (since self adjoint), and has bounded inverse.
- $R(e^{-tA}) = D(e^{tA}) \quad \forall t \geq 0.$

Let

$$S(t) := e^{-tA}, \quad t \geq 0.$$

Then

- $\{S(t) : t \geq 0\}$  is a strongly continuous semigroup on  $H$  with

$$\left\| \frac{S(t)\varphi - \varphi}{t} + A\varphi \right\| \rightarrow 0 \quad \text{as } t \rightarrow 0.$$

- $-A$  is the infinitesimal generator of  $\mathcal{S}$ , i.e.,

$$-A\varphi := \lim_{t \rightarrow 0} \frac{S(t)\varphi - \varphi}{t}, \quad \varphi \in D(-A)$$

where

$$D(-A) := \left\{ \varphi \in H : \lim_{t \rightarrow 0} \frac{S(t)\varphi - \varphi}{t} \text{ exists} \right\}.$$



# Final value problem (FVP)

Let  $\tau > 0$ ,  $\varphi_\tau \in H$  and  $f \in L^1([0, \tau], H)$ .

Consider the **final value problem** (FVP):

$$\frac{d}{dt}u(t) + Au(t) = f(t), \quad u(\tau) = \varphi_\tau. \quad (2)$$

Suppose  $u$  is a solution of (2). Then

$$u(t) = e^{-tA}\varphi_0 + \int_0^t e^{-(t-s)A}f(s)ds, \quad u(\tau) = \varphi_\tau,$$

where  $\varphi_0 := u(0)$ . In particular,

$$\varphi_\tau = u(\tau) = e^{-\tau A}\varphi_0 + \int_0^\tau e^{-(\tau-s)A}f(s)ds.$$

## Theorem

Let  $\varphi_\tau \in H$  and  $f \in L^1([0, \tau], H)$ . If the FVP (2) has a solution  $u(\cdot)$  with  $u(\tau) = \varphi_\tau$ , then

$$\psi(t) := \varphi_\tau - \int_t^\tau e^{-(\tau-s)A} f(s) ds$$

belongs to  $D(e^{(\tau-t)A})$  and

$$u(t) = e^{(\tau-t)A} \psi(t).$$

In the above, if  $f = 0$ , then

$$u(t) = e^{(\tau-t)A} \varphi_\tau.$$

- Since  $A$  is an unbounded operator,

*Small error in  $\varphi_\tau$  can lead to large error in the solution.*

## Proof of theorem.

Let  $\varphi_0 := u(0)$ . Then

$$u(t) = e^{-tA}\varphi_0 + \int_0^t e^{-(t-s)A}f(s)ds. \quad (3)$$

In particular,

$$\varphi_\tau = e^{-\tau A}\varphi_0 + \int_0^\tau e^{-(\tau-s)A}f(s)ds.$$

Since  $e^{-\tau A}\varphi_0 \in D(e^{\tau A})$ ,

$$\varphi_\tau - \int_0^\tau e^{-(\tau-s)A}f(s)ds = e^{-\tau A}\varphi_0 \in D(e^{\tau A}).$$

Hence,

$$\varphi_0 = e^{\tau A}\left(\varphi_\tau - \int_0^\tau e^{-(\tau-s)A}f(s)ds\right).$$



## Continues.

Therefore, (3) implies

$$\begin{aligned}u(t) &= e^{-tA} e^{\tau A} \left( \varphi_{\tau} - \int_0^{\tau} e^{-(\tau-s)A} f(s) ds \right) + \int_0^t e^{-(t-s)A} f(s) ds \\ &= e^{(\tau-t)A} \left( \varphi_{\tau} - \int_0^{\tau} e^{-(\tau-s)A} f(s) ds \right) + \int_0^t e^{-(t-s)A} f(s) ds.\end{aligned}$$

That is,

$$\begin{aligned}e^{-(\tau-t)A} u(t) &= \left( \varphi_{\tau} - \int_0^{\tau} e^{-(\tau-s)A} f(s) ds \right) \\ &\quad + e^{-(\tau-t)A} \int_0^t e^{-(t-s)A} f(s) ds \\ &= \varphi_{\tau} - e^{-(\tau-t)A} \int_0^{\tau} e^{-(t-s)A} f(s) ds \\ &\quad + e^{-(\tau-t)A} \int_0^t e^{-(t-s)A} f(s) ds.\end{aligned}$$

Continues.

Hence,

$$e^{-(\tau-t)A}u(t) = \varphi_\tau - e^{-(\tau-t)A} \int_t^\tau e^{-(t-s)A}f(s)ds.$$

Thus,

$$\varphi_\tau - \int_t^\tau e^{-(\tau-s)A}f(s)ds \in D(e^{(\tau-t)A})$$

and

$$u(t) = e^{(\tau-t)A} \left( \varphi_\tau - \int_t^\tau e^{-(\tau-s)A}f(s)ds \right).$$



In view of the above theorem, we introduce the following definition.

### Definition

If  $\varphi_\tau \in H$  and  $f \in L^1([0, \tau], H)$  are such that

$$\psi(t) := \varphi_\tau - \int_t^\tau e^{-(\tau-s)A} f(s) ds \quad \forall t \in [0, \tau]$$

belongs to  $D(e^{(\tau-t)A})$ , then  $u(\cdot)$  defined by

$$u(t) = e^{(\tau-t)A} \psi(t)$$

is called the **mild solution** of the FVP (2).

# FVP as operator equation

The problem of finding a mild solution  $u(\cdot)$  of the FVP with  $u(\tau) = \varphi_\tau$  can be posed as a problem of solving the operator equation

$$\mathcal{A}_t u(t) = \psi(t), \quad (4)$$

where

$$\begin{aligned} \mathcal{A}_t \varphi &:= e^{-(\tau-t)A} \varphi, \quad \varphi \in H, \\ \psi(t) &:= \varphi_\tau - \int_t^\tau e^{-(\tau-s)A} f(s) ds. \end{aligned}$$

Note that:

- $\mathcal{A}_t$  is an injective bounded self adjoint operator.
- $R(\mathcal{A}_t) = D(e^{(\tau-t)A})$  is dense in  $H$ .
- $\mathcal{A}_t^{-1} = e^{(\tau-t)A} : R(\mathcal{A}_t) \rightarrow H$  is not continuous.

Hence, (4) is ill-posed.

- A mild solution is not necessary to be a solution of the FVP:

### Theorem

Let  $\varphi_\tau \in D(e^{\tau A})$  and let  $u : [0, \tau] \rightarrow H$  be defined by  $u(t) = e^{(\tau-t)A}\varphi_\tau$ ,  $t \geq 0$ . Then  $u$  is a solution of the FVP

$$u_t + Au(t) = 0, \quad u(\tau) = \varphi_\tau$$

if and only if  $\varphi_\tau \in D(Ae^{\tau A})$ .



## Proof.

For  $t \geq 0$  and  $h > 0$ ,

$$\frac{u(t+h) - u(t)}{h} = \frac{e^{(\tau-t-h)A}\varphi_\tau - e^{(\tau-t)A}\varphi_\tau}{h} = \frac{e^{-hA}u(t) - u(t)}{h}.$$

Since  $-A$  is the infinitesimal generator of the semigroup  $\{e^{-hA} : h \geq 0\}$ ,

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{u(t+h) - u(t)}{h} \text{ exists} &\iff u(t) \in D(-A) \\ &\iff \varphi_\tau \in D(Ae^{\tau A}). \end{aligned}$$

Thus,  $u'(t)$  exists for every  $t \geq 0$  iff  $e^{\tau A}\varphi_\tau \in D(-A)$  iff  $\varphi_\tau \in D(Ae^{\tau A})$ , and in that case  $u'(t) = -Au(t)$ ,  $u(\tau) = \varphi_\tau$ .  $\square$

# Truncated spectral regularization (TRS)

Let  $\varphi_\tau$  and  $f \in L^1([0, \tau], H)$ .

Recall that, the mild solution of the FVP is

$$u(t) = e^{(\tau-t)A}\psi(t) = \int_0^\infty e^{(\tau-t)\lambda} dE_\lambda(\psi(t)) \quad (5)$$

whenever  $\psi(t) := \varphi_\tau - \int_t^\tau e^{-(\tau-s)A}f(s)ds$  belongs to  $D(e^\tau A)$ .

*Since small error in the data  $(\varphi_\tau, f)$  can lead to large error in the solution  $u(\cdot)$ , we have to look for a **regularized solution** which depends continuously on the data  $(\varphi_\tau, f)$ .*

Looking at the expression in (5) for the mild solution, we define such a regularized solution as

$$u_\beta(t) = \int_0^\beta e^{(\tau-t)\lambda} dE_\lambda(\psi(t)) \quad (6)$$

for each  $\beta > 0$ .

The following theorem shows that  $u_\beta(\cdot)$  is an approximation of  $u(\cdot)$  for large  $\beta$ .

## Theorem

*Under the assumption  $\psi(t) \in D(e^{\tau A})$ ,*

$$\|u(t) - u_{\beta}(t)\| \rightarrow 0 \quad \text{as } \beta \rightarrow \infty.$$

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$$\|u(t) - u_{\beta}(t)\| \rightarrow 0 \quad \text{as } \beta \rightarrow \infty.$$

## Proof.

Since

$$\|u(t)\|^2 = \int_0^{\infty} e^{2(\tau-t)\lambda} d\|E_{\lambda}(\psi(t))\|^2 < \infty,$$

we obtain

$$\|u(t) - u_{\beta}(t)\|^2 = \int_{\beta}^{\infty} e^{2(\tau-t)\lambda} d\|E_{\lambda}(\psi(t))\|^2 \rightarrow 0 \quad \text{as } \beta \rightarrow \infty.$$



Now, we show that

- $u_\beta(\cdot)$  is stable under perturbations in the data  $(\varphi_\tau, f)$ .

Suppose  $\tilde{\varphi}_\tau \in H$  and  $\tilde{f} \in L^1([0, \tau], H)$  are the noisy data, in place of the actual data  $\varphi_\tau$  and  $f$ , respectively.

Let

$$\tilde{u}_\beta(t) = \int_0^\beta e^{(\tau-t)\lambda} dE_\lambda(\tilde{\psi}(t)),$$

where

$$\tilde{\psi}(t) := \tilde{\varphi}_\tau - \int_t^\tau e^{-(\tau-s)A} \tilde{f}(s) ds.$$

## Theorem

Let  $\varphi_\tau, \tilde{\varphi}_\tau \in H$  and  $f, \tilde{f} \in L^1([0, \tau], H)$ . Then for each  $t \in [0, \tau]$  and  $\beta > 0$ ,

$$\begin{aligned}\|u_\beta(t) - \tilde{u}_\beta(t)\| &\leq e^{(\tau-t)\beta} \|\psi(t) - \tilde{\psi}(t)\| \\ &\leq e^{(\tau-t)\beta} (\|\varphi_\tau - \tilde{\varphi}_\tau\| + \|f - \tilde{f}\|_1).\end{aligned}$$

Suppose  $\|\varphi_\tau - \tilde{\varphi}_\tau\| + \|f - \tilde{f}\|_1 \leq \delta$  for some  $\delta > 0$ . Then we obtain

$$\|u_\beta(t) - \tilde{u}_\beta(t)\| \leq e^{(\tau-t)\beta} \delta.$$

### Observation:

- For a fixed  $\beta > 0$ ,

$$\|u_\beta(t) - \tilde{u}_\beta(t)\| \rightarrow 0 \quad \text{as} \quad \delta \rightarrow 0.$$

- $u_\beta(t)$  is stable under perturbations in the data  $(\varphi_\tau, f)$ .

From the above theorem we have

## Theorem

Let  $\varphi_\tau, \tilde{\varphi}_\tau \in H$  and  $f, \tilde{f} \in L^1([0, \tau], H)$  such that

$$\|\varphi_\tau - \tilde{\varphi}_\tau\| + \|f - \tilde{f}\|_1 \leq \delta$$

for some  $\delta > 0$ . Then for each  $t \in [0, \tau]$  and  $\beta > 0$ ,

$$\|u(t) - \tilde{u}_\beta(t)\| \leq \|u(t) - u_\beta(t)\| + e^{(\tau-t)\beta} \delta.$$

$$\beta \approx \frac{1}{\tau - t} \log \left( \frac{1}{\delta^p} \right), \quad 0 < p < 1,$$

$\Rightarrow$

$$\|u(t) - \tilde{u}_\beta(t)\| = o(1) \quad \text{as } \delta \rightarrow 0.$$



## Proof of Theorem.

We observe that

$$\psi(t) - \tilde{\psi}(t) = \varphi_t - \tilde{\varphi}_\tau - \int_t^\tau e^{-(\tau-s)A} (\tilde{f}(s) - f(s)) ds$$

and

$$u_\beta(t) - \tilde{u}_\beta(t) = \int_0^\beta e^{(\tau-t)\lambda} dE_\lambda(\psi(t) - \tilde{\psi}(t)).$$

Note that

$$\begin{aligned} \|\psi(t) - \tilde{\psi}(t)\| &\leq \|\varphi_t - \tilde{\varphi}_\tau\| + \int_t^\tau \|e^{-(\tau-s)A}\| \|f(s) - \tilde{f}(s)\| ds \\ &\leq \|\varphi_t - \tilde{\varphi}_\tau\| + \int_t^\tau \|f(s) - \tilde{f}(s)\| ds \\ &\leq \|\varphi_t - \tilde{\varphi}_\tau\| + \|f - \tilde{f}\|_1. \end{aligned}$$



Continues.

Hence,

$$\begin{aligned}\|u_\beta(t) - \tilde{u}_\beta(t)\|^2 &= \int_0^\beta e^{2(\tau-t)\lambda} dE_\lambda \|\psi(t) - \tilde{\psi}(t)\|^2 \\ &\leq e^{2(\tau-t)\beta} \|\psi(t) - \tilde{\psi}(t)\|^2\end{aligned}$$

Thus,

$$\begin{aligned}\|u_\beta(t) - \tilde{u}_\beta(t)\| &\leq e^{2(\tau-t)\beta} \|\psi(t) - \tilde{\psi}(t)\| \\ &\leq e^{2(\tau-t)\beta} (\|\varphi_t - \tilde{\varphi}_\tau\| + \|f - \tilde{f}\|_1).\end{aligned}$$



Continues.

Hence,

$$\begin{aligned}\|u_\beta(t) - \tilde{u}_\beta(t)\|^2 &= \int_0^\beta e^{2(\tau-t)\lambda} dE_\lambda \|\psi(t) - \tilde{\psi}(t)\|^2 \\ &\leq e^{2(\tau-t)\beta} \|\psi(t) - \tilde{\psi}(t)\|^2\end{aligned}$$

Thus,

$$\begin{aligned}\|u_\beta(t) - \tilde{u}_\beta(t)\| &\leq e^{2(\tau-t)\beta} \|\psi(t) - \tilde{\psi}(t)\| \\ &\leq e^{2(\tau-t)\beta} (\|\varphi_t - \tilde{\varphi}_\tau\| + \|f - \tilde{f}\|_1).\end{aligned}$$



Next we obtain an estimate for the error under an additional smoothness assumption on  $u(\cdot)$ .

## Theorem

Suppose  $\varphi_\tau \in H$  and  $f \in L^1([0, \tau], H)$  are such that for each  $t \in [0, \tau)$ ,  $\psi(t) \in D(e^{\tau A})$  and there exists a monotonically increasing continuous function  $h_t(\cdot) : [0, \tau] \rightarrow [0, \infty)$  such that

- (i)  $h_t(\lambda) \rightarrow \infty$  as  $\lambda \rightarrow \infty$ ,
- (i)  $u(t) \in D(h_t(A))$ ,
- (ii)  $\|h_t(A)u(t)\| \leq \rho_t$  for some  $\rho_t > 0$ .

Then

$$\|u(t) - u_\beta(t)\| \leq \frac{\rho_t}{h_t(\beta)}.$$

Proof.

Recall that

$$u(t) = e^{(\tau-t)A}\psi(t).$$

Hence,

$$\begin{aligned}\|u(t) - u_\beta(t)\|^2 &= \int_\beta^\infty e^{2(\tau-t)\lambda} d\|E_\lambda(\psi(t))\|^2 \\ &= \int_\beta^\infty \frac{1}{h_t(\lambda)^2} h_t(\lambda)^2 e^{2(\tau-t)\lambda} d\|E_\lambda(\psi(t))\|^2 \\ &\leq \frac{1}{h_t(\beta)^2} \int_\beta^\infty h_t(\lambda)^2 e^{2(\tau-t)\lambda} d\|E_\lambda(\psi(t))\|^2\end{aligned}$$



Continues.

By the assumption,

$$\begin{aligned}\int_0^\infty h_t(\lambda) e^{(\tau-t)\lambda} d\|E_\lambda(\psi(t))\|^2 &= \|h_t(A) e^{(\tau-t)A} \psi(t)\|^2 \\ &= \|h_t(A) u(t)\|^2 \leq \rho_t^2.\end{aligned}$$

Hence, we have

$$\|u(t) - u_\beta(t)\| \leq \rho_t / h_t(\beta).$$



Combining the last two theorems, we obtain the following.

Combining the last two theorems, we obtain the following.

### Theorem

Suppose  $\tilde{\varphi}_\tau$  and  $\tilde{f}$  are noisy data such that

$$\|\varphi_\tau - \tilde{\varphi}_\tau\| + \|f - \tilde{f}\|_1 \leq \delta$$

for some noise level  $\delta > 0$ . Then

$$\|u_\beta(t) - \tilde{u}_\beta(t)\| \leq e^{(\tau-t)\beta} \delta.$$

If  $\rho_t > 0$  and  $h_t(\cdot)$  are as in last theorem, then we have

$$\|u(t) - \tilde{u}_\beta(t)\| \leq \frac{\rho_t}{h_t(\beta)} + e^{(\tau-t)\beta} \delta.$$



## Theorem

Let

$$\xi_t(\lambda) := h_t(\lambda)e^{(\tau-t)\lambda}, \quad \lambda > 0$$

and

$$\beta = \beta_t := \xi_t^{-1}(\rho/\delta).$$

Then

$$\|u(t) - \tilde{u}_\beta(t)\| \leq \frac{2\rho}{h(\xi_t^{-1}(\rho/\delta))}.$$

In particular,

$$\|u(t) - \tilde{u}_\beta(t)\| \rightarrow 0 \quad \text{as} \quad \delta \rightarrow 0.$$

## Proof.

Note that

$$\begin{aligned}\frac{\rho_t}{h_t(\beta)} = e^{(\tau-t)\beta\delta} &\iff \xi_t(\beta) := h_t(\beta)e^{(\tau-t)\beta} = \frac{\rho_t}{\delta} \\ &\iff \beta = \xi_t^{-1}(\rho_t/\delta).\end{aligned}$$

Thus, for the choice of  $\beta = \xi_t^{-1}(\rho_t/\delta)$ ,

$$\begin{aligned}\|u(t) - \tilde{u}_\beta(t)\| &\leq \frac{\rho_t}{h_t(\beta)} + e^{(\tau-t)\beta\delta} \\ &\leq \frac{2\rho}{h(\xi_t^{-1}(\rho/\delta))}\end{aligned}$$

Since  $h(\xi_t^{-1}(\rho_t/)) \rightarrow \infty$  as  $\rightarrow 0$ .

$$\|u(t) - \tilde{u}_\beta(t)\| \rightarrow 0 \quad \text{as} \quad \rightarrow 0.$$



# Remarks on optimality

Recall that the operator  $\mathcal{A}_t : H \rightarrow H$  defined by

$$\mathcal{A}_t \varphi := e^{-(\tau-t)A} \varphi, \quad \varphi \in H$$

is injective, continuous, self adjoint, with  $R(\mathcal{A}_t)$  dense in  $H$ .

Therefore,

- $u(\cdot)$  is a generalized solution

$$\mathcal{A}_t u(t) = \varphi_\tau - \int_t^\tau e^{-(\tau-s)A} f(s) ds \quad (7)$$

if and only if it is a solution.

Let  $u(t)$  be the solution of (7) and let  $u_\alpha^L(\cdot)$  be the Lavrentie regularized solution, i.e.,

$$(\mathcal{A}_t + \alpha I) u_\alpha^L(t) = \psi(t) := \varphi_\tau - \int_t^\tau e^{-(\tau-s)A} f(s) ds.$$

Then, from the standard theory, we know that

$$\|u(t) - u_\alpha^L(t)\| \rightarrow 0 \quad \text{as} \quad \alpha \rightarrow 0$$

and

$$\|u_\alpha^L(t) - \tilde{u}_\alpha^L(t)\| \leq \frac{\delta}{\alpha}. \quad (8)$$

Note that the estimate

$$\|u_\beta(t) - \tilde{u}_\beta(t)\| \leq \delta e^{(\tau-t)\beta}$$

obtained earlier is same as (8) if we take  $\beta$  such that

$$e^{(\tau-t)\beta} = \frac{1}{\alpha}.$$

That is,

$$\beta = \frac{1}{\tau - t} \ln \left( \frac{1}{\alpha} \right).$$

Next, suppose

$$u(t) = \mathcal{A}_t v(t) \quad \text{with} \quad \|v(t)\| \leq \rho_t, \quad (9)$$

equivalently,

$$u(t) \in D(e^{(\tau-t)A}) \quad \text{with} \quad \|e^{(\tau-t)A}u(t)\| \leq \rho_t. \quad (10)$$

Then we have the estimate

$$\|u(t) - u_\alpha^L(t)\| \leq \rho_t \alpha.$$

Under the choice  $\beta := \frac{1}{\tau-t} \ln\left(\frac{1}{\alpha}\right)$ , the above estimate takes the form

$$\|u(t) - u_\alpha^L(t)\| \leq \rho_t e^{-(\tau-t)\beta}. \quad (11)$$

This is same as the estimate obtained earlier for  $\|u(t) - u_\beta(t)\|$  under the (10) .

Thus, we can conclude:

If  $h_t(\lambda) := e^{(\tau-t)\lambda}$ , then the the estimate obtained under TSR is same as the order optimal rate possible for the Lavrentive regularization for the source condition (9), if

$$\beta = \frac{1}{\tau - t} \ln \left( \frac{1}{\alpha} \right) \quad \text{and} \quad \alpha = \sqrt{\delta/\rho},$$

that is, if

$$\beta := \frac{1}{2(\tau - t)} \ln \left( \frac{\rho}{\delta} \right).$$

Similar conclusion can be made for a general  $h_t(\cdot)$  as well.

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Thank you for your attention