# Quadratic Finite Element Methods for the Obstacle Problem 

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## Outline

- The Obstacle Problem
- Conforming Linear and Quadratic Methods
- Error Estimates
- Conclusions


## Obstacle Problem

Find $u \in \mathcal{K}$ such that

$$
J(u)=\min _{v \in \mathcal{K}} J(v),
$$

where

$$
\begin{gathered}
J(v)=\frac{1}{2} \int_{\Omega}|\nabla v|^{2} d x-\int_{\Omega} f v d x, \\
f \in L^{2}(\Omega), g \in H^{1 / 2}(\partial \Omega), \\
\chi \in H^{1}(\Omega) \cap C(\bar{\Omega}) \text { with } \chi \leq g \text { on } \partial \Omega, \\
H^{1}(\Omega):=\left\{v \in L^{2}(\Omega): \nabla v \in\left[L^{2}(\Omega)\right]^{d}\right\}, \\
\mathcal{K}:=\left\{v \in H^{1}(\Omega): v \geq \chi \text { a.e. in } \Omega, v=g \text { on } \partial \Omega\right\},
\end{gathered}
$$

$\Omega$ is a polyhedral domain in $\mathbb{R}^{d}(1 \leq d \leq 3)$.

## Obstacle Problem

- The obstacle problem is a prototype model for variational inequalities of the first kind.
- The obstacle problem arises in contact mechanics, fluid flow and finance.
- Numerical approximation of the obstacle problem is interesting due to the existence of free boundary.


## Obstacle Problem

The weak formulation of the obstacle problem is to find $u \in \mathcal{K}$ such that

$$
a(u, v-u) \geq(f, v-u) \quad \forall v \in \mathcal{K} .
$$

Here

$$
\begin{gathered}
\mathcal{K}:=\left\{v \in H^{1}(\Omega): v \geq \chi \text { a.e. in } \Omega, v=g \text { on } \partial \Omega\right\}, \\
a(w, v)=\int_{\Omega} \nabla w \cdot \nabla v d x, \\
(f, v)=\int_{\Omega} f v d x .
\end{gathered}
$$

## Obstacle Problem

The weak formulation of the obstacle problem is to find $u \in \mathcal{K}$ such that

$$
a(u, v-u) \geq(f, v-u) \quad \forall v \in \mathcal{K} .
$$

If $u \in H^{2}(\Omega)$, then

$$
\begin{aligned}
&-\Delta u \geq f \quad \text { in } \quad \Omega, \\
&-\Delta u=f \text { in } \quad\{u>\chi\}, \\
&(-\Delta u-f, u-\chi)=0, \\
& \llbracket \nabla u \rrbracket=0 \quad \text { on } \quad \partial\{u=\chi\}, \\
& \llbracket u \rrbracket=0 \text { on } \quad
\end{aligned} \quad\{u=\chi\} .
$$

## Obstacle Problem

The weak formulation of the obstacle problem is to find $u \in \mathcal{K}$ such that

$$
a(u, v-u) \geq(f, v-u) \quad \forall v \in \mathcal{K} .
$$

Define $\lambda \in H^{-1}(\Omega)$ by

$$
\langle\lambda, v\rangle=a(u, v)-(f, v) \quad \forall v \in H_{0}^{1}(\Omega) .
$$

Then

$$
\begin{aligned}
\langle\lambda, v-u\rangle & \geq 0 \quad \forall v \in \mathcal{K}, \\
\langle\lambda, v\rangle & \geq 0 \quad \forall v \in H_{0}^{1}(\Omega) \text { with } v \geq 0 .
\end{aligned}
$$

## Obstacle Problem

Unlike linear elliptic problems, $C^{\infty}$ data do not imply a $C^{\infty}$ solution for obstacle problem.

Regularity Result : If $f \in L^{\infty}(\Omega) \cap B V(\Omega)$ and $\chi \in C^{3}(\bar{\Omega})$ and $\partial \Omega$ is sufficiently smooth, then $u \in W^{s, p}(\Omega)$ for all $1<p<\infty$ and $s<2+1 / p$. (Brezis 1971)

Example: Let $\Omega=(-1,1), f \equiv 0$ and $\chi(x)=1-2 x^{2}$.

$$
u(x):= \begin{cases}-4\left(-1+\frac{1}{\sqrt{2}}\right)(1+x) & \text { if } x<-1+\frac{1}{\sqrt{2}}, \\ -4\left(1-\frac{1}{\sqrt{2}}\right)(x-1) & \text { if } x>1-\frac{1}{\sqrt{2}}, \\ 1-2 x^{2} & \text { otherwise. }\end{cases}
$$

## Obstacle Problem



## FEM and Approximation

Let $\mathcal{T}_{h}$ be regular triangulation of $\Omega$. For $r \geq 1$, define finite element space

$$
V_{h}:=\left\{v \in C(\bar{\Omega}):\left.v\right|_{T} \in P_{r}(T), \forall T \in \mathcal{T}_{h}\right\},
$$

where $P_{r}(T)$ is the space of polynomials of total degree less than or equal to $r$.
The following approximation holds: Let $v \in H^{m}(T)$. Then there is some $I_{h} v \in V_{h}$ such that

$$
\left\|v-I_{h} v\right\|_{H^{k}(T)} \leq C h_{T}^{\mu-k}|v|_{H^{m}(T)}
$$

where $\mu=\min \{m, r+1\}, 0 \leq k \leq \mu, h_{T}$ is the diameter of $T$ and $C$ is a positive constant independent of $T$ and $\mathcal{T}_{h}$.

## Numerical Methods

- Falk, 1974: A conforming linear finite element method is studied. Linear order of convergence is derived with obstacle constraints at the vertices. This approach works in both two and three dimensions.
- Brezzi, Hager and Raviart,1977: Conforming quadratic finite element methods were studied. The quadratic FEM in two dimensions incorporate obstacle constraints at the midpoints of the edges. Error estimate of order $h^{3 / 2-\epsilon}$ is derived.
- Wang 2002: Revisited the analysis in Brezzi et al, 1977, the error analysis relaxes the assumption that the length of the free boundary is finite.


## Numerical Methods

- Wang, Han and Cheng, 2010: Studied linear and quadratic DG methods for two dimensional problem.
- Antonietti, Beirao da Veiga, and Verani, 2013. Studied the first order mimetic difference methods.
- Carstensen and Köhler, 2017. Linear CR Nonconforming FEM for two dimensional problem.
- Gustafsson, Stenberg, and Videman, 2017. Study mixed and stabilized methods for two dimensional problem.
- Gaddam and Gudi, 2018. Bubbles enriched quadratic FEM for three dimensional problem.
- Wang et al. 2018. Linear and quadratic virtual element methods for two dimensional problem are studied.


## Linear FEM

$\mathcal{T}_{h}=$ regular triangulation of $\Omega$,
$\mathcal{V}_{h}=$ set of vertices in $\mathcal{T}_{h}$.


Define

$$
\begin{aligned}
V_{h} & =\left\{v_{h} \in H_{0}^{1}(\Omega):\left.v_{h}\right|_{T} \in P_{1}(T), T \in \mathcal{T}_{h}\right\}, \\
\mathcal{K}_{h} & =\left\{v_{h} \in V_{h}: v_{h}(p) \geq \chi(p), \forall p \in \mathcal{V}_{h}\right\} .
\end{aligned}
$$

FEM: Find $u_{h} \in \mathcal{K}_{h}$ such that (Falk 1974)

$$
a\left(u_{h}, v_{h}-u_{h}\right) \geq\left(f, v_{h}-u_{h}\right) \quad \forall v_{h} \in \mathcal{K}_{h} .
$$

## A priori Error Analysis

Let $I_{h} u$ be the Lagrange interpolation of $u$, i.e.,

$$
I_{h} u(p)=u(p) \text { for all } p \in \mathcal{V}_{h} .
$$

It is easy to see that $I_{h} u \geq I_{h} \chi$ and $u_{h} \geq I_{h} \chi$ in $\Omega$.
Define the sets $\mathcal{T}_{+}, \mathcal{T}_{0}$ and $\mathcal{T}_{f}$ by

$$
\begin{aligned}
\mathcal{T}_{+} & =\left\{T \in \mathcal{T}_{h}: u>\chi \text { on } T\right\}, \\
\mathcal{T}_{0} & =\left\{T \in \mathcal{T}_{h}: u \equiv \chi \text { on } T\right\}, \\
\mathcal{T}_{f} & =\left\{T \in \mathcal{T}_{h}: T \notin \mathcal{T}_{+} \text {and } T \notin \mathcal{T}_{0}\right\} .
\end{aligned}
$$

Let $u, \chi \in H^{2}(\Omega)$. Now if $\lambda:=-\Delta u-f$, then

$$
\lambda \geq 0 \text { in } \Omega \text { and } \lambda \equiv 0 \text { on any } T \in \mathcal{T}_{+} .
$$

## A priori Error Analysis

## Note that

$$
\begin{aligned}
\left\|\nabla\left(u-u_{h}\right)\right\|^{2}= & a\left(u-u_{h}, u-I_{h} u\right)+a\left(u, I_{h} u-u_{h}\right) \\
& \quad-a\left(u_{h}, I_{h} u-u_{h}\right) \\
\leq & a\left(u-u_{h}, u-I_{h} u\right)+a\left(u, I_{h} u-u_{h}\right)-\left(f, I_{h} u-u_{h}\right) \\
\leq & a\left(u-u_{h}, u-I_{h} u\right)+\left(\lambda, I_{h} u-u_{h}\right) \\
\lesssim & h|u|_{H^{2}(\Omega)}\left\|\nabla\left(u-u_{h}\right)\right\|+\left(\lambda, I_{h} u-u_{h}\right) \\
\lesssim & h|u|_{H^{2}(\Omega)}\left\|\nabla\left(u-u_{h}\right)\right\|+\sum_{T \in \mathcal{T}_{0}} \int_{T} \lambda\left(I_{h} u-u_{h}\right) d x \\
& +\sum_{T \in \mathcal{T}_{f}} \int_{T} \lambda\left(I_{h} u-u_{h}\right) d x .
\end{aligned}
$$

## A priori Error Analysis

Since for any $T \in \mathcal{T}_{0}$, there holds $u \equiv \chi$ on $T$ and

$$
\int_{T} \lambda\left(I_{h} u-u_{h}\right) d x=\int_{T} \lambda\left(I_{h} \chi-u_{h}\right) d x \leq 0 .
$$

For any $T \in \mathcal{T}_{f}$,

$$
\begin{aligned}
\int_{T} \lambda\left(I_{h} u-u_{h}\right) d x & =\int_{T} \lambda\left(I_{h}(u-\chi)+I_{h} \chi-u_{h}\right) d x \\
& \leq \int_{T} \lambda I_{h}(u-\chi) d x \\
& =\int_{T} \lambda\left(I_{h}(u-\chi)-(u-\chi)\right) d x \\
& \lesssim h^{2}\|\lambda\||u-\chi|_{H^{2}(\Omega)} .
\end{aligned}
$$

A priori Error Analysis

Therefore

$$
\left\|\nabla\left(u-u_{h}\right)\right\| \lesssim h\left(|u|_{H^{2}(\Omega)}+|\chi|_{H^{2}(\Omega)}+\|f\|\right) .
$$

(Falk 1974)

## Quadratic FEM

$\mathcal{T}_{h}=$ regular triangulation of $\Omega \subset \mathbb{R}^{2}$,
$\mathcal{V}_{h}=\left\{\right.$ vertices of triangles in $\left.\mathcal{T}_{h}\right\}$,
$\mathcal{M}_{h}=\left\{\right.$ mid points of the edges in $\left.\mathcal{T}_{h}\right\}$.


Define

$$
\begin{aligned}
V_{h} & =\left\{v_{h} \in H_{0}^{1}(\Omega):\left.v_{h}\right|_{T} \in P_{2}(T), T \in \mathcal{T}_{h}\right\}, \\
\mathcal{K}_{h} & =\left\{v_{h} \in V_{h}: v_{h}(p) \geq \chi(p), \forall p \in \mathcal{M}_{h}\right\} .
\end{aligned}
$$

FEM: Find $u_{h} \in \mathcal{K}_{h}$ such that (Brezzi et al. 1977)

$$
a\left(u_{h}, v_{h}-u_{h}\right) \geq\left(f, v_{h}-u_{h}\right) \quad \forall v_{h} \in \mathcal{K}_{h} .
$$

## Quadratic FEM

The quadrature formula

$$
\int_{T} w d x \approx \frac{|T|}{3} \sum_{p \in \mathcal{M}_{T}} w(p)
$$

is exact for quadratic polynomials. Here $\mathcal{M}_{T}$ is the set of the midpoints of the three edges of $T$.

This implies if a quadratic polynomial $v$ is nonnegative at the midpoints of a triangle $T$, then

$$
\int_{T} v d x \geq 0 .
$$

## A priori Error Analysis

Let $I_{h} u$ be the Lagrange interpolation of $u$, i.e.,

$$
I_{h} u(p)=u(p) \text { for all } p \in \mathcal{V}_{h} \cup \mathcal{M}_{h} .
$$

Now $I_{h} u \nsupseteq I_{h} \chi$ and $u_{h} \nsupseteq I_{h} \chi$ in $\Omega$, but $I_{h} u \in \mathcal{K}_{h}$. This implies for any $T \in \mathcal{T}_{h}$ that

$$
\begin{array}{r}
\int_{T}\left(I_{h} u-I_{h} \chi\right) d x \geq 0, \\
\int_{T}\left(u_{h}-I_{h} \chi\right) d x \geq 0 .
\end{array}
$$

## A priori Error Analysis

Recall the sets $\mathcal{T}_{+}, \mathcal{T}_{0}$ and $\mathcal{T}_{f}$ by

$$
\begin{aligned}
\mathcal{T}_{+} & =\left\{T \in \mathcal{T}_{h}: u>\chi \text { on } T\right\}, \\
\mathcal{T}_{0} & =\left\{T \in \mathcal{T}_{h}: u \equiv \chi \text { on } T\right\}, \\
\mathcal{T}_{f} & =\left\{T \in \mathcal{T}_{h}: T \notin \mathcal{T}_{+} \text {and } T \notin \mathcal{T}_{0}\right\} .
\end{aligned}
$$

Let $f \in H^{1}(\Omega), \chi \in H^{3}(\Omega)$.
Then $u \in H^{5 / 2-\epsilon}(\Omega)$ and $\lambda:=-\Delta u-f \in H^{1 / 2-\epsilon}(\Omega)$ for any $\epsilon>0$. Further

$$
\lambda \geq 0 \text { in } \Omega \text { and } \lambda \equiv 0 \text { on any } T \in \mathcal{T}_{+} .
$$

## A priori Error Analysis

Note that with $s=5 / 2-\epsilon$,

$$
\begin{aligned}
\left\|\nabla\left(u-u_{h}\right)\right\|^{2}= & a\left(u-u_{h}, u-I_{h} u\right)+a\left(u, I_{h} u-u_{h}\right) \\
& -a\left(u_{h}, I_{h} u-u_{h}\right) \\
\leq & a\left(u-u_{h}, u-I_{h} u\right)+a\left(u, I_{h} u-u_{h}\right)-\left(f, I_{h} u-u_{h}\right) \\
\leq & a\left(u-u_{h}, u-I_{h} u\right)+\left(\lambda, I_{h} u-u_{h}\right) \\
\lesssim & h^{s-1}|u|_{H^{s}(\Omega)}\left\|\nabla\left(u-u_{h}\right)\right\|+\left(\lambda, I_{h} u-u_{h}\right) \\
\lesssim & h^{s-1}|u|_{H^{s}(\Omega)}\left\|\nabla\left(u-u_{h}\right)\right\|+\sum_{T \in \mathcal{T}_{0}} \int_{T} \lambda\left(I_{h} u-u_{h}\right) d x \\
& +\sum_{T \in \mathcal{T}_{f}} \int_{T} \lambda\left(I_{h} u-u_{h}\right) d x .
\end{aligned}
$$

## A priori Error Analysis

For any $T \in \mathcal{T}_{0}$, there holds $u \equiv \chi$ on $T$ and

$$
\begin{aligned}
\int_{T} \lambda\left(I_{h} u-u_{h}\right) d x & =\int_{T} \lambda\left(I_{h} \chi-u_{h}\right) d x \\
& \leq \int_{T}(\lambda-\bar{\lambda})\left(I_{h} \chi-u_{h}\right) d x \\
& =\int_{T}(\lambda-\bar{\lambda})\left(I_{h} u-u_{h}\right) d x \\
& =\int_{T}(\lambda-\bar{\lambda})\left(\left(I_{h} u-u_{h}\right)-\overline{\left(I_{h} u-u_{h}\right)}\right) d x \\
& \lesssim h^{3 / 2-\epsilon}|\lambda|_{H^{1 / 2-\epsilon}(\Omega)}| | \nabla\left(I_{h} u-u_{h}\right) \|, \\
& \text { where }\left.\quad \bar{v}\right|_{T}:=\frac{1}{|T|} \int_{T} v d x
\end{aligned}
$$

## A priori Error Analysis

For any $T \in \mathcal{T}_{f}$, similarly

$$
\begin{aligned}
\int_{T} \lambda\left(I_{h} u-u_{h}\right) d x \lesssim & h^{3-\epsilon}|\lambda|_{H^{1 / 2-\epsilon}(\Omega)}\left(|\chi|_{H^{3}(\Omega)}+|u|_{H^{5 / 2-\epsilon}(\Omega)}\right) \\
& +h^{3 / 2-\epsilon}|\lambda|_{H^{1 / 2-\epsilon}(\Omega)}\left\|\nabla\left(I_{h} u-u_{h}\right)\right\| .
\end{aligned}
$$

A priori error estimate: If $f \in H^{1}(\Omega)$ and $\chi \in H^{3}(\Omega)$ and $u \in W^{s, p}(\Omega)$ for all $1<p<\infty$ and $s<2+1 / p$, then

$$
\left\|u-u_{h}\right\|_{1} \leq C h^{3 / 2-\epsilon}, \text { for all } \epsilon>0 .
$$

(Brezzi et al. 1977) (Wang 2002)

## Numerical Results

Let $\Omega$ be the square with corners
$\{(-1,0),(0,-1),(1,0),(0,1)\}$. Let $\chi=1-2 r^{2}$, where $r=\sqrt{x^{2}+y^{2}}$. Let $r_{0}=(\sqrt{2}-1) / \sqrt{2}$.
The load function $f$ is taken as

$$
f(r):= \begin{cases}4 & \text { if } r<r_{0}, \\ 4 r_{0} / r & \text { if } r \geq r_{0} .\end{cases}
$$

Then the solution $u$ is given by

$$
u(r):= \begin{cases}1-2 r^{2} & \text { if } r<r_{0} \\ 4 r_{0}(1-r) & \text { if } r \geq r_{0}\end{cases}
$$

## Numerical Results

Order of convergence:

| $h$ | $\left\\|\nabla\left(u-u_{h}\right)\right\\|$ | order of conv. |
| :---: | :---: | :---: |
| $\sqrt{2} / 4$ | 0.206211469561149 | - |
| $\sqrt{2} / 8$ | 0.058342275497902 | 1.821 |
| $\sqrt{2} / 16$ | 0.025124856349493 | 1.215 |
| $\sqrt{2} / 32$ | 0.007971135017375 | 1.656 |
| $\sqrt{2} / 64$ | 0.002583671405642 | 1.625 |
| $\sqrt{2} / 128$ | 0.000931014496396 | 1.472 |
| $\sqrt{2} / 256$ | 0.000323678406046 | 1.524 |

## Quadratic FEM for 3D Problem

Let $\mathcal{T}_{h}$ be a regular triangulation of $\Omega \subset \mathbb{R}^{3}$.
For any $T \in \mathcal{T}_{h}$, let $b_{T} \in H_{0}^{1}(T)$ be a quartic bubble function. Define

$$
\begin{aligned}
V_{h} & =\left\{v_{h} \in H_{0}^{1}(\Omega):\left.v_{h}\right|_{T} \in P_{2}(T) \oplus b_{T}, T \in \mathcal{T}_{h}\right\}, \\
\mathcal{K}_{h} & =\left\{v_{h} \in V_{h}: \int_{T} v_{h} d x \geq \int_{T} \chi d x, \forall v \in \mathcal{T}_{h}\right\} .
\end{aligned}
$$

FEM: Find $u_{h} \in \mathcal{K}_{h}$ such that (Gaddam and Gudi, 2016)

$$
a\left(u_{h}, v_{h}-u_{h}\right) \geq\left(f, v_{h}-u_{h}\right) \quad \forall v_{h} \in \mathcal{K}_{h} .
$$

## Quadratic FEM for 3D Problem

Define $I_{h} u \in V_{h}$ to be the interpolation of $u$ by

$$
\begin{aligned}
& I_{h} u(p):=u(p) \text { for all vertices of } \mathcal{T}_{h}, \\
& I_{h} u(p):=u(p) \text { for all midpoints of the edges of } \mathcal{T}_{h},
\end{aligned}
$$

and

$$
\int_{T} I_{h} u d x=\int_{T} u d x \text { for all } T \in \mathcal{T}_{h} .
$$

Degrees of freedom for $I_{h}$ on each $T$ is 11 which is the same as the dimension of $P_{2}(T) \oplus b_{T}$.

Further since $u \geq \chi$ in $\Omega$, we have

$$
\int_{T} I_{h} u d x=\int_{T} u d x \geq \int_{T} \chi d x \text { for all } T \in \mathcal{T}_{h} .
$$

## A Priori Error Estimate

Let $f \in H^{1}(\Omega)$ and $\chi \in H^{3}(\Omega)$ and $u \in H^{5 / 2-\epsilon}(\Omega)$ for any $\epsilon>0$. Further assume that $u \in W^{s, p}(\Omega)$, where $s<2+1 / p$ and $1<p<\infty$.

Then there holds

$$
\left\|u-u_{h}\right\|_{1} \leq C h^{3 / 2-\epsilon} \text { for all } \epsilon>0 .
$$

## Numerical Experiment

Let $\Omega=(0,1)^{3}$ and the obstacle function be $\chi \equiv 0$. The forcing function $f$ is taken to be

$$
f(x, y, z):= \begin{cases}-4\left(2 r^{2}+3\left(r^{2}-r_{0}^{2}\right)\right) & \text { if } r>r_{0}, \\ -8 r_{0}^{2}\left(1-r^{2}+r_{0}^{2}\right) & \text { if } r \leq r_{0},\end{cases}
$$

where $r=\left(x^{2}+y^{2}+z^{2}\right)^{1 / 2}$ and $r_{0}=0.7$.
The nonhomogeneous Dirichlet boundary condition is taken in such a way that the solution $u$ is given by

$$
u(x, y, z)=\left(\max \left(r^{2}-r_{0}^{2}, 0\right)\right)^{2} .
$$

## Numerical Experiment

Order of convergence:

| $h$ | $\left\\|\nabla\left(u-u_{h}\right)\right\\|_{L^{2}(\Omega)}$ | order |
| :---: | :---: | :---: |
| 0.3467 | $1.8500 \mathrm{e}-001$ | - |
| 0.1733 | $5.6046 \mathrm{e}-002$ | 1.3596 |
| 0.0867 | $1.9210 \mathrm{e}-002$ | 1.4112 |
| 0.0433 | $7.1151 \mathrm{e}-003$ | 1.3636 |

## Numerical Experiment



## Conclusions

A quadratic finite element enriched with element wise bubble functions with integral constraints is designed and shown to be optimal (up to the regularity)

Numerical experiments confirm the theoretical results.
A reliable and efficient (partially) a posteriori error estimator for these methods is also derived.

## Reference

- S. Gaddam and T. Gudi. Bubbles enriched quadratic finite element method for the 3D-elliptic obstacle problem. Comput. Meth. Appl. Math., 18 (2018), pp. 223-236

